

OLRE16



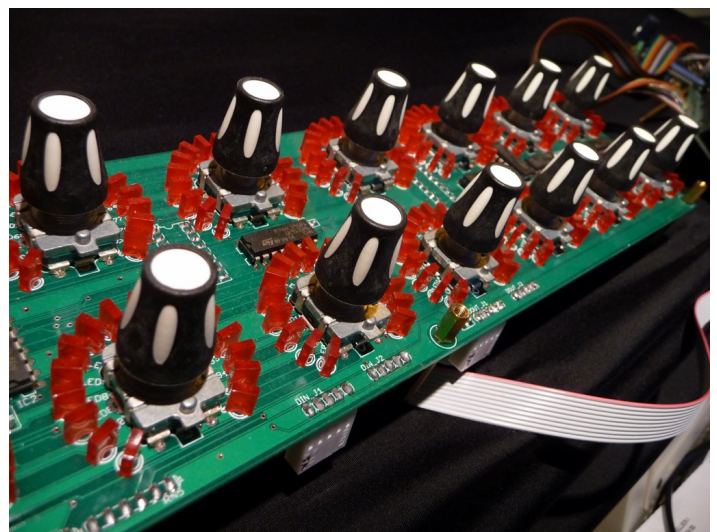
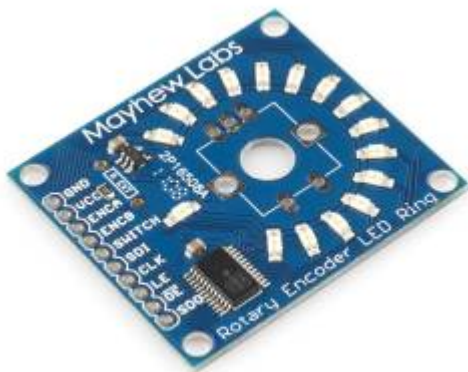
Under Development



Introduction

The Start point was a search about a good LED-Ring for encoders [Forum thread](#) .
2 existing solutions , but that could be improved :

- The **LED Ring Breakout Board from Sparkfun** Big, single blue color and only 16 segments.

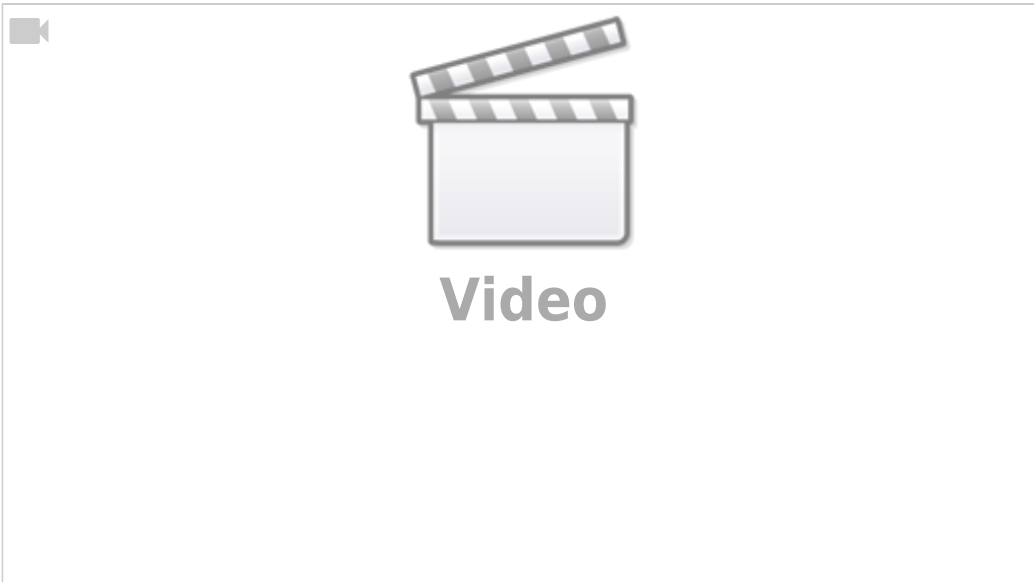


- Fairlightii **LRE8x2CS**..Monochrome, Only 16 segments

Improvement Guidelines

1. **RGB LEDs** for enhanced user feedback and further possible interactions
2. **31 segments in a 270° open ring + 1 index/step segment.**
3. **A straight aligned 16 rings board would fit in a 19" rack**
4. **Small screen to display values like step#, name of the parameter**
5. PCB-mount under front panel has to be easy and should stack the other board which supports the encoders.
6. Interface with to mios32 core has to be easy.

The Result



LED Driving

Sizing

We expect 16 RGB LED rings encoders. So let's do the math : **16 Encoders * 32 LEDs * 3 colors = 1536 lines**

Let's transpose this to a classical matrixed SRIO chain design:

16 * 3 (cathodes) * 32 (anodes)
= 48 inputs + 32 outputs
= 6*DIN + 4*DOUT

Core-External Driving Concept : TLC5958

In theory it's possible to drive such a SRIO setup but in fact buses and resistors/R networks are very hard to place and will it consume a lot of constant refresh process.

After a look on the different brands and models of LED driver IC **Texas Instruments TLC5958** appeared as a good compromise to drive a lot of RGB LEDs without overloading the core. Designed to be a LED Display driver, its original purpose and features would allow large-sized RGB-LED-based display setups

TLC5958 Datasheet

This Design note from Texas Instruments helps in understanding how to design around the TLC:

Build high density, high refresh rate, multiplexing LED panel with TLC5958

TLC5958 Features

1. **48 Channels Constant Current Sink Output**
2. **Global Brightness Control (BC) : 3-Bit (8 Step)**

3. **Color Brightness Control (CC) for Each Color Group: 9-Bit (512 Step), Three Groups.**
4. **Grayscale(GS) Control with Multiplexed Enhanced Spectrum(ES) PWM: 16bit**
5. **48K bit Grayscale Data Memory Support**
6. **32-multiplexing** (*32 lines mux * 48 channels = 1536!*)
7. **SPI Data Transfer Rate: 25MHz**
8. LED Open Detection (LOD)
9. Thermal Shut Down (TSD)
10. IREF Resistor Short Protection (ISP)
11. Delay Switching to Prevent Inrush Current
12. Pre-charge FET to Avoid Ghosting Phenomenon
13. Daisy-Chain!

Mechanical Design

Initial goal was to fit 16 LED Rings + bottom OLEDs in a 19" rack.

19" = 440mm.

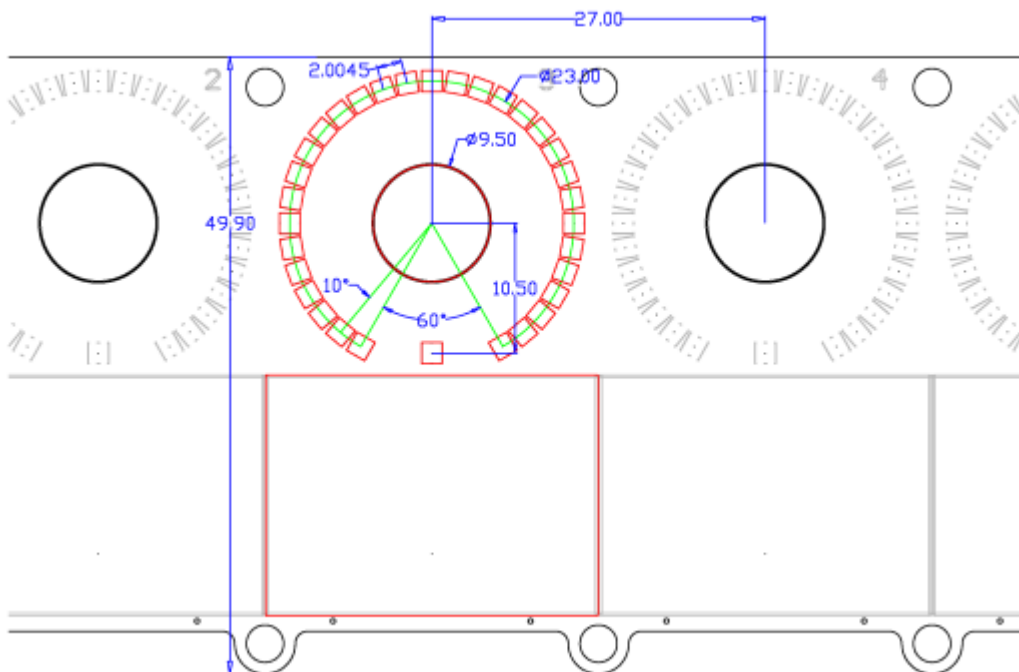
440 - (4mm case side)*2 = 432 mm.

432/16 LED-Rings = 27mm / LED-Ring

Luckily an OLED 0.96" is exactly sized 27mm

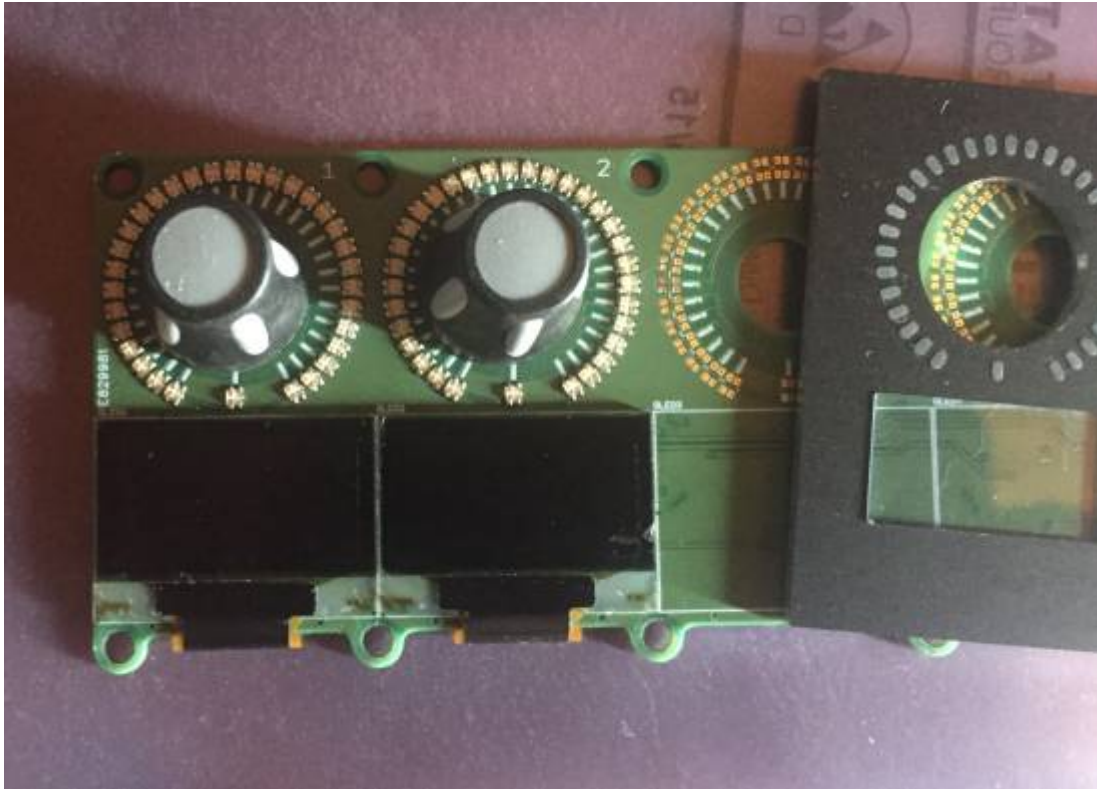
The total height is 50mm, with the mounting holes.

1 Rack Unit size height (44.5mm) was impossible with the OLED displays. Note that it's possible without.



By reversing OLED displays, the active area is closer to the ring.

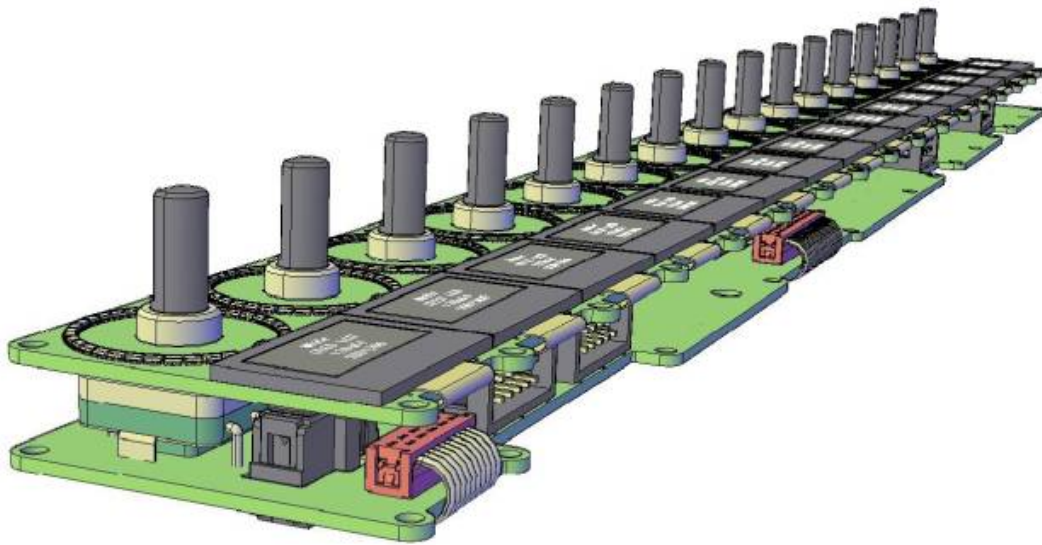
Distance between SMD LEDs center is somewhat close (2.0046mm) But not impossible, for proof:



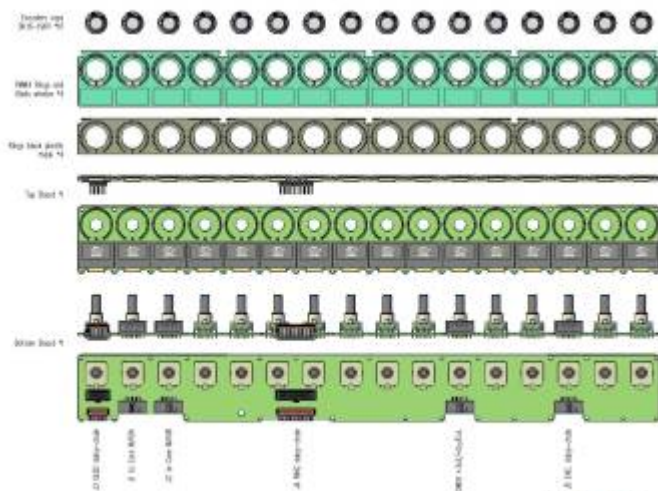
Conceptual views

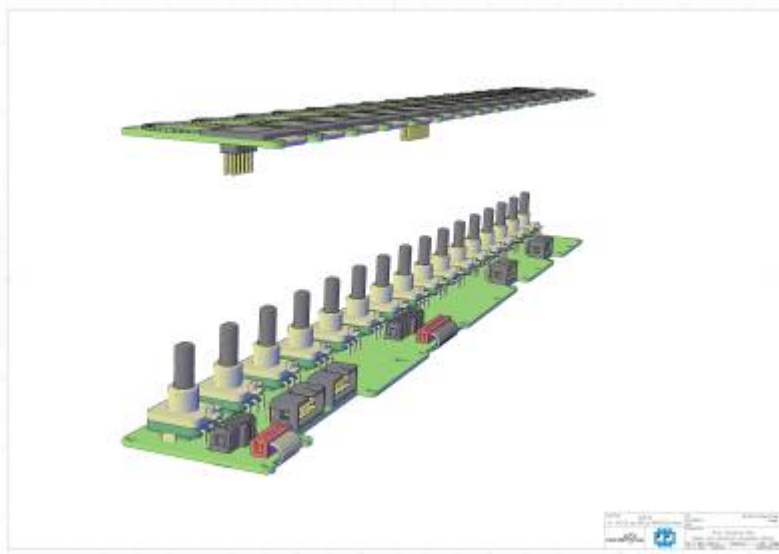
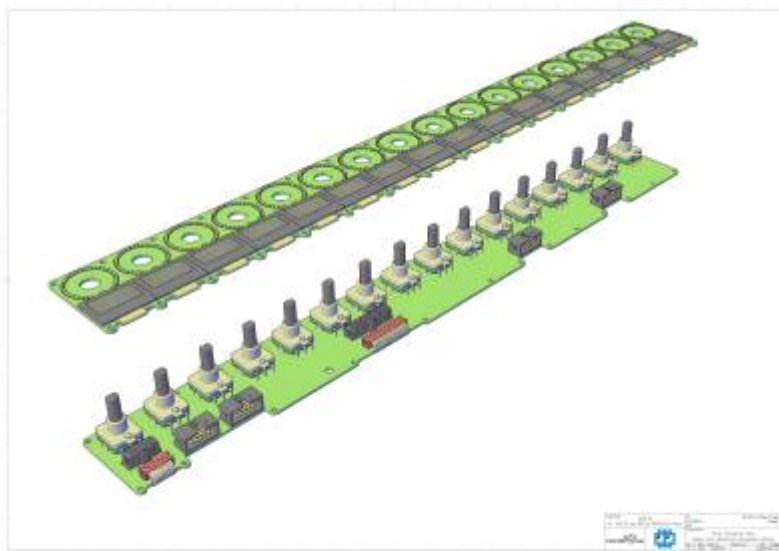
The module consists in a 2 pcbs sandwich, spaced 10mm .

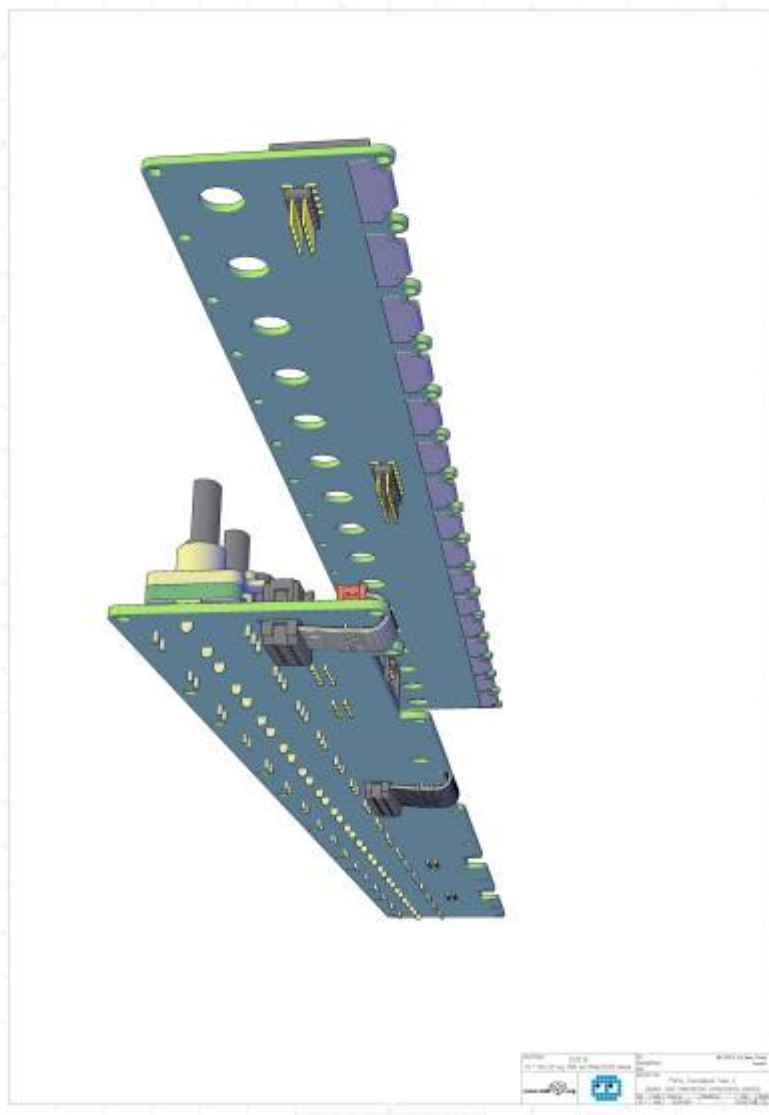
Global size is 432mm Width * 50mm Height * 22mm Depth



Date/Time: 01/05/24 IP: 192.168.1.100 User: admin Password: admin1234567890	Device: 192.168.1.100 Model: 192.168.1.100 Version: 192.168.1.100 Status: 192.168.1.100
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Prototyping

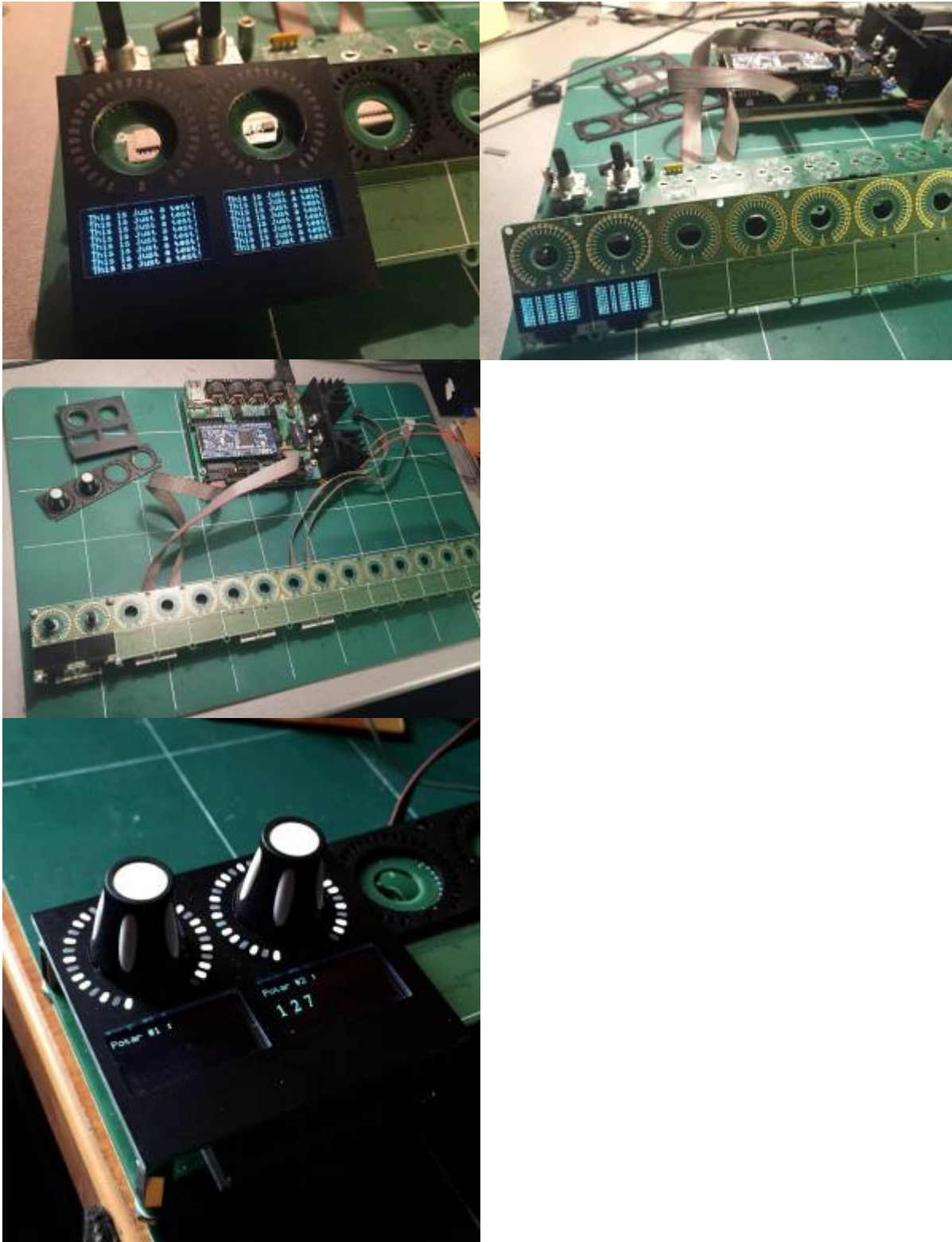
The first prototype was tested with an [LPC1769 Core](#). For testing purposes only 2 LED-rings were set up in order not to waste components for development. The first software module written was added in an app, but integration in the SEQ V4 app was not possible because a lack of Memory on the LPC17 Core...

Meanwhile the migration to [STM32F4 Core](#), an independent external clocking circuit for the GSCLK and the address lines was designed. STM32F4 Core will just have to provide a PWM a RESET signal and receive an interrupt from this circuit to get the End Of Frame.

Data Transfer

A serialized design has been chosen to provide data to TLC. Prototype feature only 2 steps but the CORE works like there's 4 modules of 16 steps connected. In order to benchmark reactivity and Transfer time, Core send data for 4 modules ($4 \times 16 \times 32 \times 3 \times 16 \text{bit} = 12 \text{KBytes}$). Through an emulated software SPI bus, for this 64 rings Data Sending takes less than 5ms . Different colors and patterns

like relative value(-64/63), keyboard(B&W keys) etc... were tested.





GrayScale Clock

Design of External GrayScale Clock for the TLC was tricky.

257 clock periods and halt for some 1.5~2.5 μ s are needed for each address line

TLC would receive a VSYNC command at the end of the 32th address line to prepare the new frame datas.

The first approach was to provide a PWM at 800KHz and put it back to the LPC on a TMR CAP Input, use 2 MAT outputs to provide a line period and gate(NOR) the PWM with it.

*First issue, halting time after the 257 periods wasn't constant and dependent of PWM frequency.
Second issue, much I/O used only for this purpose.*

Electronic Design

TLC related Design

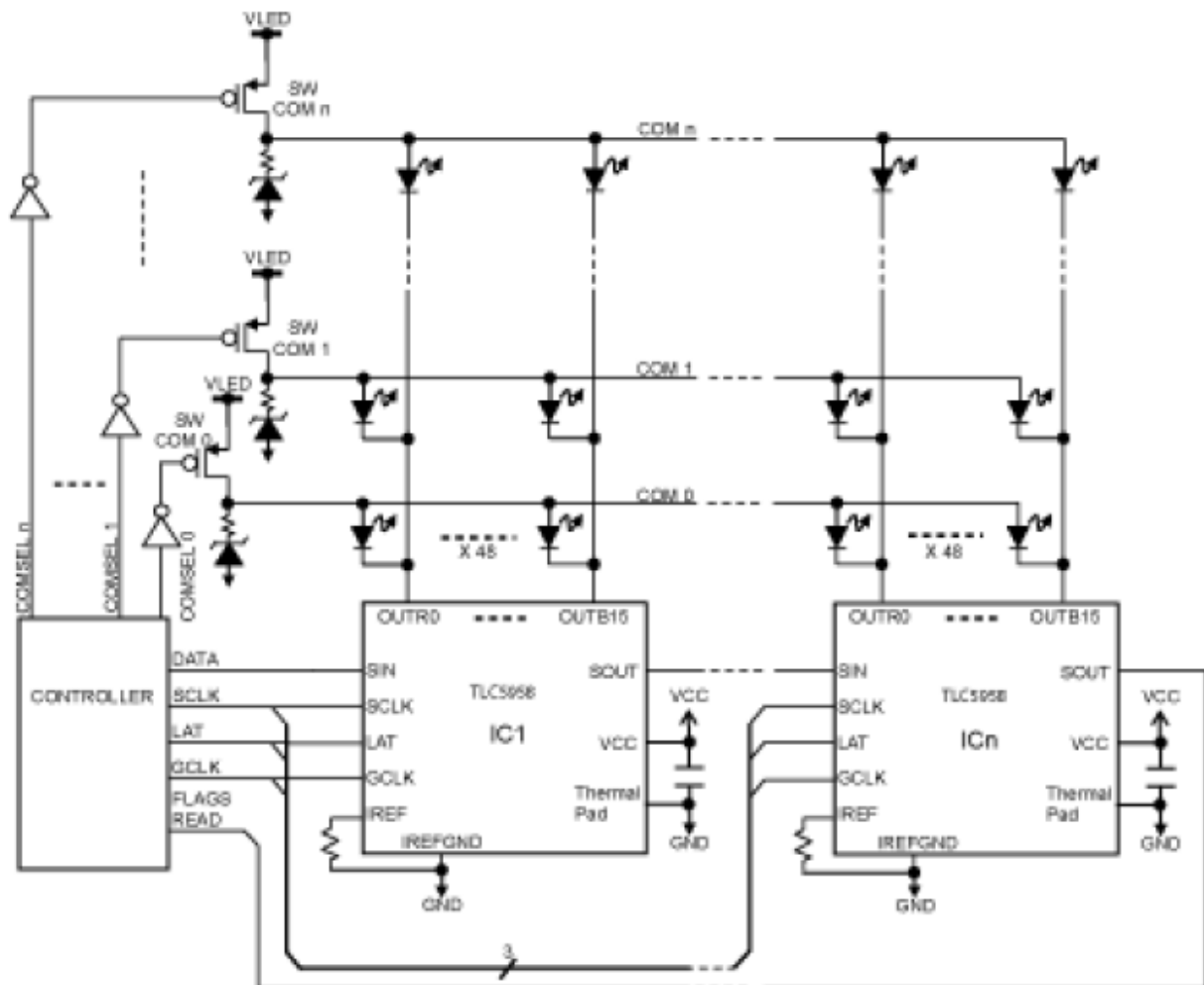


Figure 1. Typical Application Circuit (Multiple Daisy Chained TLC5958s)

Example: 8+8 mode, Multiplexing ratio 1/32

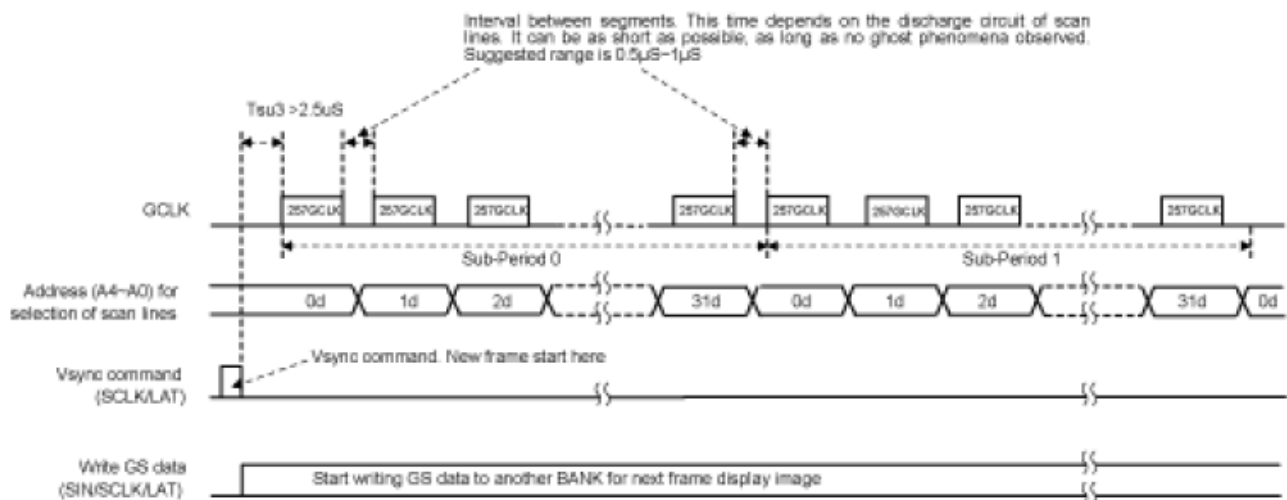


Figure 16. Controller Timing Sequence, 8+8 Mode, 32 Multiplexing

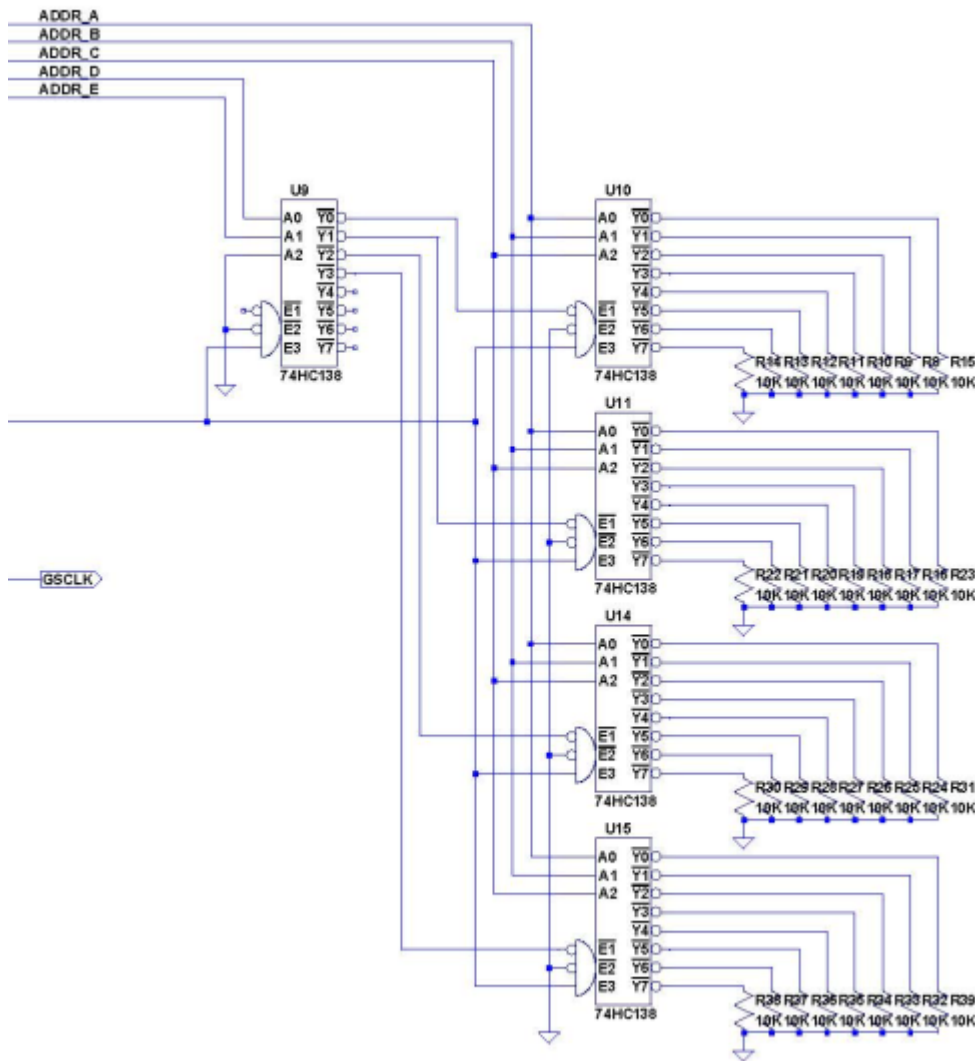
TLC is wired like on an SPI bus to Core Board. Here are connections equivalences:

- SCLK \Rightarrow SC
- DATA \Rightarrow SO
- LAT \Rightarrow RC

After a certain time given by the RC couple on U1, U1 switch back and restarts the counter. By this way we are sure to count the exact 257 Clocks needed and the interval between 2 segments is fixed by the trimpot U19.

GSCLK signal is then high during the 257 clocks period and low during the interval

Multiplexing Schematic



ADDR_x, ADDR_CLK, GSCLK are connected to the top board...

ADDR_CLK is the multiplexed lines clock . It's used to gate the PWM signal and obtain the GSCLK and of course, as a clock for the ADDR Counter U5. The counter U5 provides the coded ADDR_x lines and an EOF(End Of Frame) when 32 is reached.

To be continued...



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